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GLOBAL SOLUTIONS FOR YOUR CONTROLLING

▸ VFD / Inverter ▸ Process Control Instruments ▸ Programmable Timers
▸ Programmable Counters ▸ Power & Energy Meters ▸ Din Rail Timer
▸ PIC & HMI ▸ Temperature Controller

ME-100 SERIES
VECTOR FREQUENCY INVERTER / SOLAR INVERTER

Product Introduction :

The ME100 series of vector inverters are single-phase 220VAC and three-phase 220V/380V AC inverters lauched by MISTURA based on the market demand of small power, small size and low cost.

Industrial Application :

Machine tools, Packaging, Chemical Industry, Transmission, Fans and Pumps, Ceramic Industry, Woodworking Machine

Superior Performance :

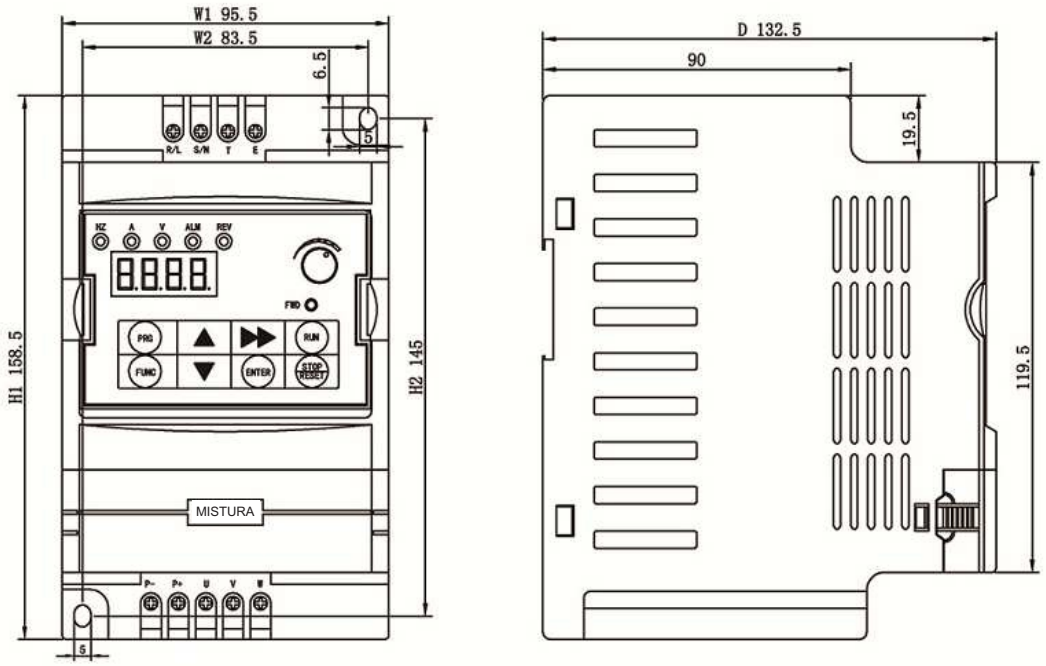
• Vector Control • Solar Inverter MPPT Control • Stong EMC Anti-Interference Capability

Technical Specification :

Item		Specification	
Input	Rated voltage,frequency	Three phase (4T Series) 380V; 50 / 60Hz three phase (2T Series) 220V: 50 / 60Hz	
	Allowable variation range of voltage	Three phase (4T Series) 320v ~ 460V three phase (2t Series) 190V ~ 250V	
Output	Voltage	4T series; 0 ~ 380V 2T series; 0 ~ 220V	
	frequency	0~600HZ	
	Overload Capacity	110% long term 150% 1 minute 180% 5 seconds	
	control mode	V / F control, simple vector control	
Control characteristics	Frequency setting resolution	Analog input	0.1% of maximum output frequency
		Digital setting	0.1HZ
	Frequency accuracy	Digital input	Within 0.2% of maximum output frequency
		Digital setting	Set the output frequency within 0.01%
	V/F control	V / F curve (voltage frequency characteristic)	The reference frequency can be set arbitrarily from 5 Hz to 600 Hz, the multi point V / F curve can be set arbitrarily, and a variety of fixed curves such as constant torque, low reduced torque 1, low reduced torque 2 and square torque can also be selected
		Torque lifting	Manual setting: 0.0 - 30.0% of rated outputAutomatic lifting: according to the output current and motor parameters, automatically determine the lifting torque
		Automatic current Limiting and voltage limiting	Whether in the process of acceleration, deceleration or stable operation, the staton current and voltage of the motor are automatically detected, and the unique algorithm is used to suppress the current and voltage within the allowable range, so as to minimize the possibility of system faulttripping

Control characteristics	Sensorless vector control		Voltage frequency characteristic	The output voltage frequency ratio is automatically adjusted according to the motor parameters and unique algorithm
			Torque characteristics	Starting torque:100% rated torque at 5.0hz (VF control) 150% rated torque at 1.5Hz (simple vector control)
			Current and voltage suppression	Fullrange current closed-loop control, completely avoid current impact, with perfect over-current and over-voltage suppression function
	Under voltage suppression in operation		Especially for the users with low grid voltage and frequent fluctuation of grid voltage, the system can maintain the longest possible operation time according to the unique algorithm and residual energy allocation strategy even if the voltage is lower than the allowable range	
Typical functions	Multi speed operation		7-segment programmable multi-stage speed control, multiple operation modes are optional.	
	PID control Rs485 communication		Built in PID controller (preset frequency). Standard configuration of RS485 communication function, a variety of communication protocols optional, with linkage synchronization control function	
	Frequency setting		Analog input	DC voltage 0 ~ 10V, DC current 0 ~ 20mA (upper and lower limit optional)
			Digital input	Operation panelsetting, RS485 interfacesetting, up / DW terminal control, and various combination settings with analog input
	output signal		Digital output	1 channel OC output and 1 channel fault relay output (TA, TB, TC), up to 14 meaning optionsTypical functions
			Analog output	One analog signal output, the output range is 0 ~ 20mA or 0-10V, which can realize the output of physical quantity such as setting frequency and output frequency
	Automatic stable operation		According to the needs, dynamic voltage stabilization, statio voltage stabilization and non voltage stabilization can be selected to obtain the most stable operation effect	
	Acceleration and deceleration time setting		0.1s ~ 999.9min continuous setting	
	braking	Energy consumption braking	The starting voltage, return differential voltage and energy consumption braking rate can be adjusted continuously	
		DC brake	Starting frequency of DC braking at shutdown: 0.00 ~ [f0.05] upper limit frequency Braking time: 0.0 - 30.0S; braking current: 0.0% - 50.0% of motor rated voltage	
	Low noise operation		Carrier frequency 1.0khz - 16.0khz can be adjusted continuously to minimize motor noise	
	Counter		One internal counter, convenient for system integration	
	Operation function		Setting of upper and lower frequency, frequency jump operation, reverse operation limit, slip frequency compensation, RS485 communication, frequency increasing, decreasing control, fault self recovery operation, etc	
display	Operation panel display	running state	Output frequency, output current, output voltage, motor speed, set frequency, module temperature, PID setting, feedback, analog input and output, etc	
		Alarm content	Output frequency, set frequency, output current, output voltage,DC voltage, module temperature and other operating parameters recorded during the last fault trip	

Protection function		Over current, over voltage, under voltage, module failure, electronic thermal relay, overheating, short circuit, internal memory failure, etc
Environmental Science	Ambient temperature	- 10 °C~ + 40 °C (if the ambient temperature is between 40 °Cand 50 °C, please reduce the rating for use)
	Ambient humidity	5% - 95% RH, no water condensation
	surrounding environment	Indoor (no direct sunlight, corrosion, flammable gas, oil mist, dust, etc.)
	altitude	Derating for more than 1000m, with 10% derating for every 1000m increase
structure	Protection level	IP 20
	Cooling mode	Air cooled with fan control
Installation mode		Wall mounted, cabinet



Voltage grade	specifications	power (kw)	Overall dimensions (mm)			Installation dimensions (mm)			Packing size (mm)			The net weight 1 (kg)
			W1	H1	D	W2	H2	φ	long	wide	height	
220VSingle phase	ME 100-2SR 75G/1.5P	0.75	95.5	158.5	132.5	83.5	145	4.5	195	132	172	1.23
	ME 100-2S0 1R5G/2.2P	1.5										
	ME 100-2S0 2R2G/4P	2.2										
380Vthree phase	ME 100-4S0 1R5G/2.2P	1.5	95.5	158.5	132.5	83.5	145	4.5	195	132	172	1.25
	ME 100-4T0 2R2G/4P	2.2										
	ME 100-4T0 004G/5.5P	4.0										

MI-150 SERIES

HIGH PERFORMANCE CURRENT VECTOR INVERTER

Type : Single Tube IGBT （0.75-11kW ）

Power range : 0.75~11KW

Voltage level : Three phase 380V

Product Introduction :

MI 150 is a high-performance VFD with MISTURA that integrates vector frequency conversion technology. With high-perfomance current vector technology, it can easily drive induction motors. High performance, high quality, high power density design, and significant improvements in ease of use, maintainability, environmental protection, installation space and design standards can further optimize theuser experience.

Application scenarios :

Mainly used in chemical industry, food, textile, plastics,mining, paper, litting metallurgy, crushers, fans, cold heading machines, CNC lathes and other scenes with large inertia. heavy load and regenerative energy feedback, providing equipment with the advantages of high response, high precision, high energy saving. etc.

Chapter Two Product standard specifications

2.1 Technical specification

Input	Rated voltage, frequency	Three-phase AC 380V.50/60H2 Single-phase AC 220 V,50/60H2	
	voltage allowed Range of change	Three-phase AC 3 80 V ~ 4 8 0V Single-phase AC220 V ~ 260 V	
Output	Voltage	0 ~ 480V 0 ~ 260V	
	Frequency	Vector control: 0~500Hz V/F control: 0~5000Hz	
	Overload capacity	G type machine: 150% rated current for 60s: 180% rated current for 3s P type machine: 120% rated current for 60s: 150% rated current for 3s.	
Control method		V/F control, speed sensorless vector control (SVC)	
Control Characteristics	Frequency setting resolution	Along input	Maximum frequency × 0.025%
		Digital settings	0.01Hz
	V/F control	V/F curve	Three methods: linear type; mult-point type: N-th power V/F curve (1.2 power, 1.4 power, 1.6 power. 1.8 power, 2 power)
		V/F separation	2 ways: full separation, semi-separation
		Torque boost	Manual setting: 0.0~30.0% of rated output Automatic lifting: automatically determine the lifting torque according to the output current and combined with with the motor parameters
		Automatic current limiting and pressure limiting	Whether during acceleration.deceleration or stable operation, it can automatically detect the motor stator current and voltage, and suppress it within the allowable range based on a unique algorithm to minimize the possibility of system fault tripping.
Control Characteristics	Inductive vector control	Voltage frequency characteristics	Automatically adjust the output voltage-to-frequency ratio based on motor parameters and unique algorithm
		Torque characteristics	Starting torque: 150% rated torque at 3.0Hz. (V/F control) 150% rated torque at 0.5Hz (vector control without speed sensor) Operating specd steady-state accuracy: ≤±0.2% rated synchronous speed Speed fluctuation: ≤±0.5% rated synchronous speed Torque response: ≤20ms (vector control without speed sensor)
		Self-determination of motor parameters	Without any restrictions, automatic parameter detection can be completed under both static and dynamic conditions of the motor to obtain the best control effect.
		Current and voltage suppression	Full current closed-loop control, completely avoiding current impact, with complete overcurrent and overvoltage suppression functions
	Undervoltage suppression during	Especially for users with low grid voltage and frequent fluctuations in grid voltage, even if the voltage is lower than the allowed voltage range, the system can maintain the longest possible operating time based on a unique algorithm and residual energy allocation strategy.	
	operation		

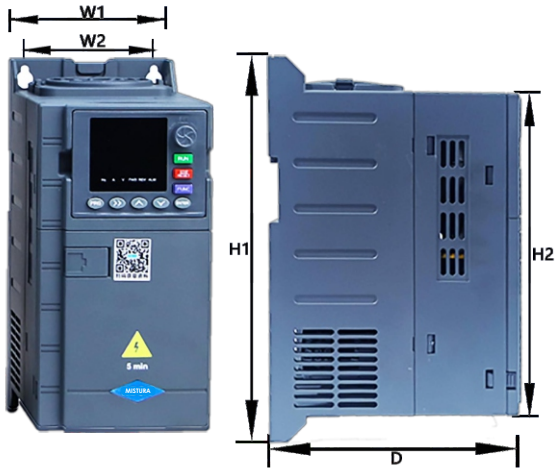
Typical function	Multi-speed and frequency operation	16-segment programmable multi-segment speed control. multiple operating modes available. Swing frequency operation: preset frequency and center frequency are adjustable, state memory and recovery after power outage	
	PID coutrol RS 485 communicati on	Built-in PID controller (frequency can be preset), standard configuration RS485 communication function	
	Frequency setting	Analog input	DC voltage 0~10V, DC current 0~20mA (upper and lower limits optional)
		digital input	Operation panel setting. RS485 interface setting, UP/DOWN terminal control, and various combination settings with analog input
	Output signal	digital output	2 Y terminal open collector outputs and 2 programmable relay outputs (TA. TB, TC), up to 58 meaning options
		Analog output	2 analog signal outputs, the output range can be flexibly set between 0~20mA or 0~10V. which can realize the output of physical quantities such as set frequency and output frequency
	Automatic voltage stabilization operation	You can choose dynamic voltage stabilization, static voltage stabilization, or unstabilized voltage according to your needs to obtain the most stable operating effect.	
	Acceleration and deceleration time setting	0.0s~6500.0s can be set continuously, S-shaped and linear modes are optional	
	brake	Energy consumpt ion brake	Energy consumption braking starting voltage, hysteresis voltage and energy consumption braking rate are continuously adjustable
		DC brake	Stop DC braking starting frequency: 0.00~[F00.10] maximum frequencyBraking time: 0.0~100.0s; Braking current: 0%~100% rated current
	Low noise operation	The carrier frequency is continuously adjustable from 0.5KHz to 16.0KHz to minimize motor noise. There are 8 operating	
	RPM tracking speed restart function	It can realize smooth restart and instantaneous stop restart function of the running motor.	
	counter	An internal counter to facilitate system integration	
	run function	Upper and lower limit frequency settings, frequency jump operation, reverse operation limit, slip frequency compensation, RS 485 communication, frequency increase and decrease control, fault self-recovery operation, etc.	
Display	Opetration panel display	run state	Output frequency, output current, output voltage, motor speed, set frequency, module temperature, PID setting, feedback amount, analog input and output, etc.
		Alarm content	There are 8 operating parameter records including output frequency, set frequency, output current, output voltage, DC voltagc, module temperature, power-on time, and running time when three faults trip.
Protective function	Overcurrent, overvoltage, undervoltage, module failure, clectronic thermal relay, overheating. short circuit, input and output phase loss. abnormal motor parameter tuning, internal memory failure, ete.		
Environment	ambient temperature	-10°C ~+40°C (environment temperature is between 40°C ~ 50°C, please derate for use)	
	ambient humidity	5% ~95%RH, no water droplets condensation	
	surroundings	Indoor (no direct sunlight, no corrosion, flammable gas, oil mist, dust, etc.)	
	surroundings	Derating for use above 1000 meters, derate by 10% for every 1000 meters.	
Structure	Protection level	IP 20	
	cooling method	Air-cooling, with fan control	
Installation method		Wall-mounted; cabinet type	

MI 150 series inverter selection guide

Model A （0.75-2.2kW）

Power	Model	W1 (mm)	H1 (mm)	D (mm)	W2 (mm)	H2 (mm)	Φ
0.75KW	MI 150-4TR75G	78	170	125	60	161	5
1.5KW	MI 150-4T01R5G						
2.2KW	MI 150-4T02R2G						

Model B 4.0-5.5kW



Power	Model	W1 (mm)	H1 (mm)	D (mm)	W2 (mm)	H2 (mm)	Φ
4KW	MI 150-4T0004G	95	210	145	78	198	5
5.5KW	MI 150-4T05R5G						

MH-550 SERIES

HIGH PERFORMANCE CURRENT VECTOR INVERTER

Type : Advanced Module IGBT

Power range : 0.75~2.2KW single phase 220V
0.75~630KW single phase 380V

Product Introduction :

MH 550 is a high-performance VFD with MISTURA that integrates vector frequency conversion technology. With high-perfomance current vector technology, it can easily drive induction motors. High performance, high quality, high power density design, and significant improvements in ease of use, maintainability, environmental protection, installation space and design standards can further optimize theuser experience.

Application scenarios :

Mainly used in chemical industry, food, textile, plastics,mining, paper, litting metallurgy, crushers, fans, cold heading machines, CNC lathes and other scenes with large inertia. heavy load and regenerative energy feedback, providing equipment with the advantages of high response, high precision, high energy saving. etc.

Chapter Two Product standard specifications

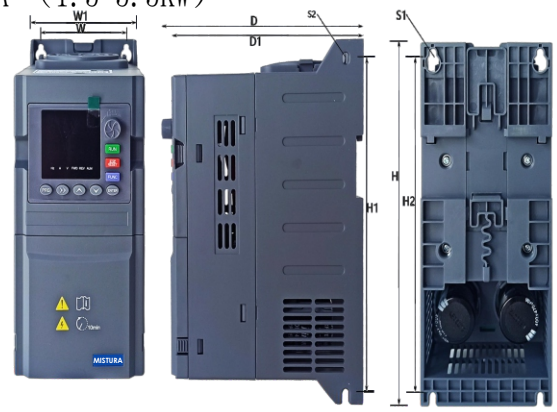
2.1 Technical specification

Input	Rated voltage, frequency	Three-phase AC 380V.50/60H2 Single-phase AC 220 V,50/60H2	
	voltage allowed Range of change	Three-phase AC 3 80 V ~ 4 8 0V Single-phase AC220 V ~ 260 V	
Output	Voltage	0 ~ 480V 0 ~ 260V	
	Frequency	Vector control: 0~500Hz V/F control: 0~5000Hz	
	Overload capacity	G type machine: 150% rated current for 60s: 180% rated current for 3s P type machine: 120% rated current for 60s: 150% rated current for 3s.	
Control method		V/F control, speed sensorless vector control (SVC)	
Control Characteristics	Frequency setting resolution	Along input	Maximum frequency × 0.025%
		Digital settings	0.01Hz
	V/F control	V/F curve	Three methods: linear type; mult-point type: N-th power V/F curve (1.2 power, 1.4 power, 1.6 power. 1.8 power, 2 power)
		V/F separation	2 ways: full separation, semi-separation
		Torque boost	Manual setting: 0.0~30.0% of rated output Automatic lifting: automatically determine the lifting torque according to the output current and combined with with the motor parameters
		Automatic current limiting and pressure limiting	Whether during acceleration.deceleration or stable operation, it can automatically detect the motor stator current and voltage, and suppress it within the allowable range based on a unique algorithm to minimize the possibility of system fault tripping.
Control Characteristics	Inductive vector control	Voltage frequency characteristics	Automatically adjust the output voltage-to-frequency ratio based on motor parameters and unique algorithm
		Torque characteristics	Starting torque: 150% rated torque at 3.0Hz. (V/F control) 150% rated torque at 0.5Hz (vector control without speed sensor) Operating specd steady-state accuracy: ≤±0.2% rated synchronous speed Speed fluctuation: ≤±0.5% rated synchronous speed Torque response: ≤20ms (vector control without speed sensor)
		Self-determination of motor parameters	Without any restrictions, automatic parameter detection can be completed under both static and dynamic conditions of the motor to obtain the best control effect.
		Current and voltage suppression	Full current closed-loop control, completely avoiding current impact, with complete overcurrent and overvoltage suppression functions
	Undervoltage suppression during	Especially for users with low grid voltage and frequent fluctuations in grid voltage, even if the voltage is lower than the allowed voltage range, the system can maintain the longest possible operating time based on a unique algorithm and residual energy allocation strategy.	
	operation		

Typical function	Multi-speed and frequency operation	16-segment programmable multi-segment speed control. multiple operating modes available. Swing frequency operation: preset frequency and center frequency are adjustable, state memory and recovery after power outage	
	PID coutrol RS 485 communicati on	Built-in PID controller (frequency can be preset), standard configuration RS485 communication function	
	Frequency setting	Analog input	DC voltage 0~10V, DC current 0~20mA (upper and lower limits optional)
		digital input	Operation panel setting. RS485 interface setting, UP/DOWN terminal control, and various combination settings with analog input
	Output signal	digital output	2 Y terminal open collector outputs and 2 programmable relay outputs (TA. TB, TC), up to 58 meaning options
		Analog output	2 analog signal outputs, the output range can be flexibly set between 0~20mA or 0~10V. which can realize the output of physical quantities such as set frequency and output frequency
	Automatic voltage stabilization operation	You can choose dynamic voltage stabilization, static voltage stabilization, or unstabilized voltage according to your needs to obtain the most stable operating effect.	
	Acceleration and deceleration time setting	0.0s~6500.0s can be set continuously, S-shaped and linear modes are optional	
	brake	Energy consumpt ion brake	Energy consumption braking starting voltage, hysteresis voltage and energy consumption braking rate are continuously adjustable
		DC brake	Stop DC braking starting frequency: 0.00~[F00.10] maximum frequencyBraking time: 0.0~100.0s; Braking current: 0%~100% rated current
	Low noise operation	The carrier frequency is continuously adjustable from 0.5KHz to 16.0KHz to minimize motor noise. There are 8 operating	
	RPM tracking speed restart function	It can realize smooth restart and instantaneous stop restart function of the running motor.	
	counter	An internal counter to facilitate system integration	
	run function	Upper and lower limit frequency settings, frequency jump operation, reverse operation limit, slip frequency compensation, RS 485 communication, frequency increase and decrease control, fault self-recovery operation, etc.	
Display	Opetration panel display	run state	Output frequency, output current, output voltage, motor speed, set frequency, module temperature, PID setting, feedback amount, analog input and output, etc.
		Alarm content	There are 8 operating parameter records including output frequency, set frequency, output current, output voltage, DC voltagc, module temperature, power-on time, and running time when three faults trip.
Protective function	Overcurrent, overvoltage, undervoltage, module failure, clectronic thermal relay, overheating. short circuit, input and output phase loss. abnormal motor parameter tuning, internal memory failure, ete.		
Environment	ambient temperature	-10°C ~+40°C (environment temperature is between 40°C ~ 50°C, please derate for use)	
	ambient humidity	5% ~95%RH, no water droplets condensation	
	surroundings	Indoor (no direct sunlight, no corrosion, flammable gas, oil mist, dust, etc.)	
	surroundings	Derating for use above 1000 meters, derate by 10% for every 1000 meters.	
Structure	Protection level	IP 20	
	cooling method	Air-cooling, with fan control	
Installation method		Wall-mounted; cabinet type	

MH 550 series inverter selection guide

Model A （1.5-5.5KW）

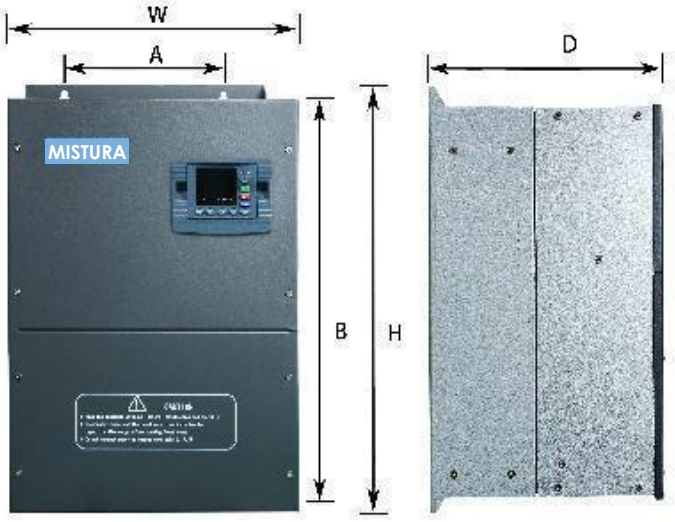


Power	Model	W (mm)	H (mm)	D (mm)	W1 (mm)	H1 (mm)	H2 (mm)	D1 (mm)	S1 (mm)	S2 (mm)
1.5kW	MH 550-2S01R5G/2.2P	95	212	149	78	194	194	142	Ø10	Ø5
2.2KW	MH 550-2S02R2G/4P									
1.5KW	MH 550-4T01R5G/2.2P									
2.2KW	MH 550-4T02R2G/4P									
4KW	MH 550-4T0004G/5.5P									
5.5KW	MH 550-4T05R5G/7.5P									

Model B （7.5-30KW）

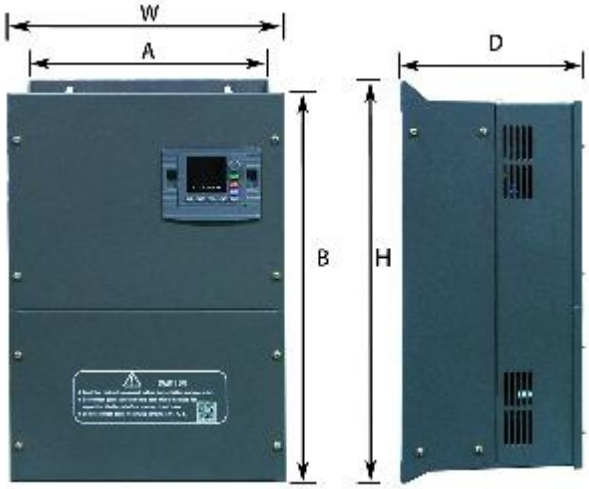
Power	Model	W1 (mm)	H1 (mm)	D (mm)	W2 (mm)	H2 (mm)	Φ
7.5KW	MH550-4T07R5G/11P	140	240	178	130	230	5.5
11KW	MH550-4T0011G/15P						
15KW	MH550-4T0015G/18.5P	205	320	195	188	305	7
18.5KW	MH550-4T18R5G/22P						
22KW	MH550-4T0022G/30P						
30KW	MH550-4T0030G/37P						

Model C （37KW）



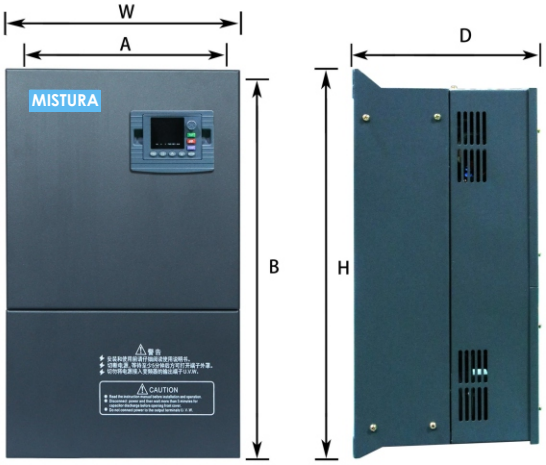
Power	Model	W (mm)	H (mm)	D (mm)	A (mm)	B (mm)	Φ
37KW	MH 550-4T0037G/45P	225	370	205	150	357	8

Model D（45-110KW）



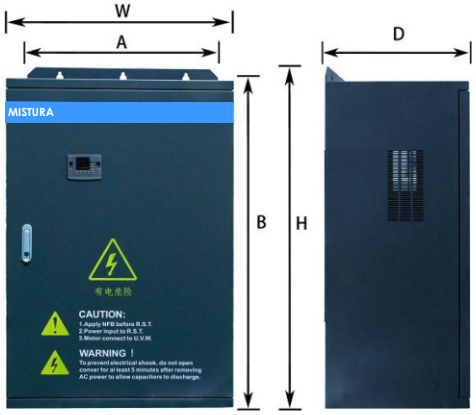
Power	Model	W (mm)	H (mm)	D (mm)	A (mm)	B (mm)	Φ
45KW	MH 550-4T0045G/55P	295	460	206	78	194	194
55KW	MH 550-4T0055G	300	460	260	78	194	194
75KW	MH 550-4T0075G/93P	320	565	281.5	78	194	194
93KW	MH 550-4T0093GH/110P	380	670	281.5	78	194	194
110KW	MH 550-4T0110GH/132P						

Model E （132-250KW）



Power	Model	W (mm)	H (mm)	D (mm)	A (mm)	B (mm)	Φ
132KW	MH 550-4T0132GH/160P	500	780	290	360	745	Hanging Φ11
160KW	MH 550-4T0160GH/185P						
185KW	MH 550-4T0185GH/200P						
220KW	MH 550-4T0220GH/250P	550	835	320	360	800	
250KW	MH 550-4T0250GH/280P						

Model F （280-400KW）



Power	Model	W (mm)	H (mm)	D (mm)	A (mm)	B (mm)	Φ
280KW	MH 550-4T0280GH/315P	700	1080	420	460	1030	Hanging Φ12
315KW	MH 550-4T0315GH/350P						
355KW	MH 550-4T0355G/400P						
400KW	MH 550-4T0400G/450P						

Indiawide Presence

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